LONG-TERM MARINE TRAFFIC MONITORING FOR ENVIRONMENTAL SAFETY IN THE AEGEAN SEA

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ABSTRACT:

The Aegean Sea is characterized by an extremely high marine safety risk, mainly due to the significant increase of the traffic of tankers from and to the Black Sea that pass through narrow straits formed by the 1600 Greek islands. Reducing the risk of a ship accident is therefore vital to all socio-economic and environmental sectors. This paper presents an online long-term marine traffic monitoring work-flow that focuses on extracting aggregated vessel risks using spatiotemporal analysis of multilayer information: vessel trajectories, vessel data, meteorological data, bathymetric / hydrographic data as well as information regarding environmentally important areas (e.g. protected high-risk areas, etc.). A web interface that enables user-friendly spatiotemporal queries is implemented at the frontend, while a series of data mining functionalities extracts aggregated statistics regarding: (a) marine risks and accident probabilities for particular areas (b) trajectories clustering information (c) general marine statistics (cargo types, etc.) and (d) correlation between spatial environmental importance and marine traffic risk. Towards this end, a set of data clustering and probabilistic graphical modelling techniques has been adopted.

1. INTRODUCTION

Conservation of the marine environment is fundamental for life on earth since the Seas cover the majority of the surface of the globe and play an essential role in weather and climate. In addition, it is necessary to minimize the risks of pollution and harm done to it by human activities, and particularly by the cargo transported by the liner shipping industry which represents about two-thirds of the value of total global trade, equating each year to more than four trillion dollars worth of goods. In this work, the target area is the Aegean Sea, which represents an example where there is high marine safety risk due to the shipping activities. Reducing the possibility of ship accidents in the Aegean Sea is important to all social, economic, environmental, and cultural sectors of Greece, since it supports and enables a significant part of the Greek economy, especially tourism.

A possible maritime accident would result in reduced investor confidence in infrastructures and transportation, the closure of fisheries, the devastation of local communities and tourism, as well as it would result in a severe impact on public health. Oil spill cleanups can cost over a millions Euros (Grey, 1999), (Kontovas et al., 2010), (Liu and Wirtz, 2006), whereas accidents involving spill of water soluble hazardous cargo are impossible to clean up. Most importantly, a huge marine accident in the Aegean would also result in long term catastrophic and irrevocable changes to the Aegean ecosystem. It is therefore obvious that it is vital to take measures towards the reduction of the disaster risk resulting in chronic pollution and permanent damage. Despite the fact that the Greek Maritime Authorities monitor activity in certain priority areas, there are no national level monitoring policies, mainly due to legal limitations when enforcing shipping

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routes in the Aegean Sea. Therefore, all involved "stakeholders" (ship companies and policy makers) would directly benefit from a monitoring system that:

- outputs optimal safe routes
- delivers real-time alerts for their ships whenever there is an increased possibility of accident
- provides policy recommendation support

These are the capabilities of the AMINESS platform¹ (Giannakopoulos et al., 2014): it will integrate information from multiple sources as well as historical maritime data that have been preprocessed, in order to provide the three expected capabilities: real-time alerting, optimal routing and policy support. In this paper, we focus on proposing a framework for long-term monitoring of ship trajectories in the context of a policy recommendation tool.

2. LONG-TERM MONITORING TOOL

2.1 Architecture, methodology and implementation issues

The purpose of the proposed long-term monitoring tool is to extract user-friendly data analytics to policy makers and general users regarding vessel traffic. It is mainly based on historical marine traffic data as its purpose is to extract long-term statistics and trends. The tool makes use of all types of spatio-temporal marine

 $^{^{1}}$ www.aminess.eu

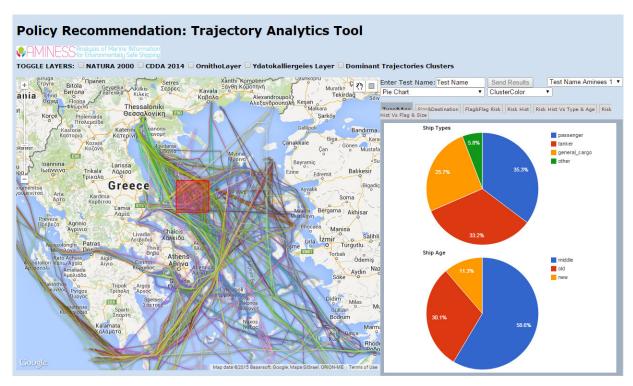


Figure 1: Screenshot of the long-term monitoring tool

data, however it will mostly focus on (a) long-term vessel trajectories (b) static vessel details and (c) dynamic spatiotemporal data (weather).

The basic submodules used in the context of the tool are the following:

- Trajectory clustering. This is the task of grouping objects based on their spatial and temporal similarity (Kisilevich et al., 2010). The goal of this submodule is therefore to group similar vessel trajectories into homogeneous categories. The output of this functionality can be considered as a set of "channel trajectories". Each channel is mapped to a single trajectory cluster and it can be considered as an aggregated average of similar trajectories. The usefulness of this functionality is twofold: (a) to provide better visualizations of large trajectory datasets and (b) to extract a more efficient and compressed representation of sets of trajectories.
- Static vessel risk estimate: this submodule aims to use Bayesian Networks in order to empirically estimate a risk measure related to each ship, given its attributes (Koromila et al., 2014). Aggregated results of this risk will be visualized in the policy recommendation tool in order to provide an image of the estimated ship risk distribution. We prefer BNs because compared to fuzzy logic approaches (e.g. (Balmat et al., 2011)) they provide a human interpretable and probabilistic modeling of the problem, allowing the straightforward incorporation of expert knowledge. In addition, they can both be empirically structured or statistically trained from data.
- Dynamic risk estimate: the goal here is similar to the previous submodule, however in that case time-dependent data is used as input to the risk model: weather data, ship traffic etc. Fuzzy logic has also been used for dynamic ship risk estimation.

In order to visualize the historical trajectories and their attributes (e.g. cluster labels, dynamic and static risks extracted by the aforementioned modules), a user-friendly web application has been developed that assists in the policy recommendations. More specifically the application accepts spatial input from the user, executes a spatiotemporal query to the system database and displays the results with several diagrams. In particular, the input to the interface consists of a rectangular area that the user draws over the area under consideration. We have focused on extracting aggregated statistics for the given bounding box through respective diagrams. Each diagram displays the spatiotemporal (in general) variability of an attribute of the trajectories that are contained in the selected area. Towards this end, a spatiotemporal query is performed on the system database using this user defined bounding box. On the server side an intersection is performed on the trajectories of the database vessels and the trajectories that are contained or intersected by that rectangular are selected and returned to the interface together with their attributes. The trajectory coordinates are stored as KML lines. This makes the trajectory retrieving process via intersection queries rather simple and fast. As soon as the intersected trajectories are retrieved, the respective attributes are aggregated and presented as statistics diagrams to the user.

The basic statistics are organized in six individual statistic types (sections), some of which contain two separate subsections. Each statistic type corresponds to a set of charts for a particular type of aggregated vessel and/or area characteristic. In each section the variability of one attribute (of the selected trajectories) is displayed. The particular statistics presented by the data analytics software are the following:

- Vessel Type
- Vessel Age
- Vessel Size

- Vessel Port (destination at the respective trajectories)
- · Vessel Flag
- Vessel Flag Ship Risk (a risk estimate given the particular ship flag)
- Risk Histogram: a histogram of the (aggregated) estimated risks.
- Risk distributions vs particular ship attributes. This functionality can be used as explanatory analysis of the risk distribution against particular ship variables and in particular:
 - Risk Histogram vs. Type
 - Risk Histogram vs. Age
 - Risk Histogram vs. Flag
 - Risk Histogram vs. Size

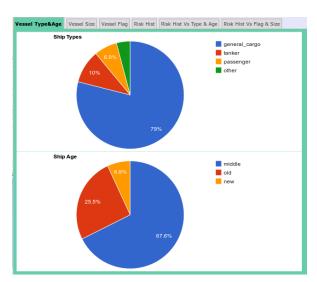


Figure 2: Example of Pie Charts (ShipType, ShipAge)

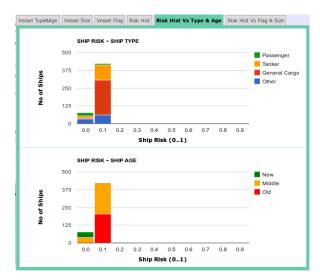


Figure 3: Example of Risk Histogram per ShipType and per ShipAge

2.2 Use-case

We have used the implemented long-term visualization interface in order to extract aggregated statistics from seven areas of major interest in the Greek marine territory. We have particularly selected 7 areas in the Greek marine territory based on their environmental importance. These areas either include protected areas (e.g. NATURA) or accommodate highly important species. Table 1 presents the names of these areas along with their respective sectors (see Figure 4).

Area Name	Sector	Sector ID
Kythera	Southern Aegean - Cretan Sea	1
Zakynthos	Ionian - Patras Gulf	2
Amorgos	Central Aegean - Corinth Gulf	3
Koufonissia	Central Aegean - Corinth Gulf	3
Kasos	Southern Aegean - Cretan Sea	1
Lemnos	Northern Aegean	4
Sporades	Northern Aegean	4

Table 1: Study areas and respective general sectors



Figure 4: General sectors distribution

For each of areas and corresponding sectors we have retrieved the trajectories that intersect with them and then aggregated their statistics, focusing on the average vessel risk. This whole process of user-defined spatio-temporal vessel trajectory retrieval is supported through the proposed policy recommendation interface. Results of aggregated risk statistics are shown in 2. This table presents:

- The average risk of the area of interest, compared to the respective sector's average risk and the overall Greek marine average risk
- The percentage of vessel trajectories that are higher than three predefined thresholds (0.4, 0.5 and 0.6), for both the areas of interest and the respective sectors.

The results of table 2 prove that:

- In all areas, the average risk is higher than the corresponding general sector's risk.
- The percentage of trajectories belonging to the three highrisk-zones is almost always significantly higher than the respective percentages in the sector's aggregates.

Area	Sector	Risk		%R > 0.4		%R > 0.5		%R > 0.6		
		Area	Sector	Overall	A	S	Α	S	A	S
Kythera	1	0.36	0.35		21	20	9	7	4	2
Zakynthos	2	0.35	0.35		17	22	6	11	2	1
Amorgos	3	0.37	0.34		41	30	20	16	2	2
Koufonissia	3	0.37	0.34		39	30	22	16	1	2
Kasos	1	0.37	0.35		23	20	9	7	5	2
Lemnos	4	0.39	0.36		29	24	12	12	8	2
Sporades	4	0.38	0.36	0.34	41	24	22	12	4	2

Table 2: Aggregated risk results. Table shows the average risk differences between each area of interest and corresponding general sectors.

3. CONCLUSIONS

In this paper we present a framework for long-term monitoring of ship trajectories in the context of a policy recommendation tool towards the reduction of ship accidents in the Aegean Sea. We describe the basic submodules and the web interface functionalities. A case study is performed on 7 environmentally sensitive areas of the Aegean Sea. For each area the spatiotemporal query produces aggregated statistics of the included vessel risks. The analysis of the average risk of each area and the comparison to corresponding larger sectors prove the importance of using the developed web tool.

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