# ULTRA-HIGH SPATIAL RESOLUTION UAV-BASED IMAGERY TO PREDICT BIOMASS IN TEMPERATE GRASSLANDS

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# ABSTRACT:

Monitoring biomass yield in grassland is of key importance to support sustainable management decisions. Especially the high spatiotemporal variety in grasslands requires rapid and cost-efficient data acquisition with a high spatial and temporal resolution. Therefore, this study aims to evaluate the comparability of UAV-based simultaneously acquired vegetation indices from a consumer-grade RGBcamera (Sony Alpha 6000) and a well-calibrated narrow-band multispectral camera (MicaSense RedEdge-M) to estimate dry matter biomass yield. The study site is an experimental grassland field in Germany with four nitrogen fertilizer levels. Biomass yield and UAV-based data for the first cut in May 2018 was analysed in this study. From the RGB-data the Plant Pigment Ratio Index (PPR) and the Normalized Green Red Difference Index (NGRDI) and from the multispectral data the Normalized Difference Vegetation Index (NDVI) are calculated as predictors for dry biomass yield. The NGRDI and NDVI perform moderately well with crossvalidation R<sup>2</sup> of 0.57 and 0.63 respectively, while the PPR performs better with an R<sup>2</sup> of 0.70. These results indicate the potential of low-cost UAV-based methods for rapid assessment of grasslands.

# 1. INTRODUCTION

Grasslands cover 40 % of the earth's terrestrial surface and are of ecological and economic importance (FAO, 2010). Besides providing ecosystem functions such as carbon sequestration, grasslands are the basis of milk and meat production, but also play a role in biofuel production (O'Mara, 2012) Monitoring biomass yield throughout the growing season is of key importance to support management decisions on grasslands. Especially on intensely managed grasslands, where nitrogen fertilizer and manure are applied regularly, precision agriculture applications are beneficial to support sustainable, site-specific management decisions on fertilizer treatment, grazing management and yield forecasting to mitigate potential negative impacts. To support these management decisions, timely and accurate information is needed on plant parameters with a high spatial and temporal resolution. However, in highly heterogeneous plant communities such as grasslands, assessing their in-field variability non-destructively to determine e.g. adequate fertilizer application still remains challenging (Schellberg and Verbruggen, 2014). Especially biomass or yield estimation, as an important parameter in assessing grassland quality and quantity, is rather laborious. Biomass yield is mostly measured manually by clipping, height sticks, rising plate meters ultrasonic sensors, handheld or vehicle-mounted or (Wachendorf, 2017). Thus, the in-field variability cannot be assessed for the entire field or only with potential disturbances and the measurements are prone to subjective judgements.

The rapid development in platform and sensor technology, e.g. miniaturization and cost-efficiency of multispectral cameras and more user-friendly platforms (UAVs), open up a new spatial scale for environmental and agricultural studies and offer a cost efficient and near-real time assessment of biomass yield with high temporal and spatial resolution (Aasen et al., 2018).

Vegetation indices derived from aerial RGB images to predict biomass in crops have been investigated in only a few studies (e.g. Bendig et al. 2015, Hunt et al. 2005, Jannoura et al. 2015). Recent studies deployed UAV-based multispectral or RGB cameras to assess grassland biomass with good results (Lussem et al., 2018; Viljanen et al., 2018).

In this contribution we want to evaluate simultaneously acquired RGB-based vegetation indices from a consumer-grade RGB-camera and a well-calibrated narrow-band multispectral camera to estimate dry biomass yield on an experimental grassland field in Germany.

# 2. MATERIAL & METHODS

The study site was established in 2017 on a conventionally managed grassland field (0.5 ha<sup>-1</sup>) in Germany (Bergisches Land region, North Rhine-Westphalia). The fertilizer treatments (0, 50, 100, 150 kg N ha<sup>-1</sup>, subsequently N1, N2, N3, N4) are applied in a chessboard-like pattern with 39 replicates per treatment, resulting in 156 plots of 36 m<sup>2</sup>. The cutting regime of three cuts per year was kept according to the local farming pattern. For this contribution we will focus on the second sampling date (May 25) of the first growth in 2018. Aerial images were acquired simultaneously with a Micasense RedEdge-M multispectral camera (MicaSense Inc., Seattle, WA, USA) and a Sony Alpha 6000 camera The MicaSense RedEdge-M camera is equipped with five distinct cameras (each 1.2 Megapixel, 47.2 ° HFOV) in the visible to near-infrared region (Table 1). Additionally, the camera has a downwelling light sensor (irradiance sensor) and a GPS. Prior and directly after the flight a grey reference panel was captured with the MicaSense RedEdge-M.

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Figure 1. Location of test-site (data source: ESRI Basemaps, Eurostat). Inset map: Orthomosaic of test site.

Band name	Center Wavelegth [nm]	Bandwidth [nm]	
Blue	475	20	
Green	560	20	
Red	668	10	
Red Edge	717	10	
Near Infrared	840	40	

Table 1. Band specifications of the MicaSense RedEdge-M camera.

The Sony Alpha 6000 is a standard RGB-camera (24 Megapixel). Both cameras were mounted simultaneously on a multirotor UAV (MK Oktokopter XL with 2-axis gimbal). The flying height was set to 35 m above ground level resulting in a ground sampling distance (GSD) of ~ 2.3 cm for the RedEdge-M, and ~ 0.7 cm for the Sony Alpha 6000. Images were acquired around 11 a.m. with stable illumination conditions.

For precise georeferencing of the images 15 ground control points (GCPs) were distributed across the test-site and measured with an RTK-GPS (Topcon GR5).

Image data was processed in the Structure-from-Motion software Photoscan v1.4 (Agisoft LLC, St. Petersburg, Russia). At least 10 markers per GCP were placed. After image alignment (*high* quality setting) the dense cloud was computed (*high* quality setting with *mild* depth filtering). The Micasense RedEdge-M dataset was calibrated by the *calibrate reflectance* function in Photoscan, using the calibration factors of the irradiance sensor and the grey reference panel. Subsequently one orthomosaic per sensor was exported with a spatial resolution of 2.5 cm. Index calculation was performed in ArcGIS Pro v2.2 (ESRI,

VI Name	Equation	Reference
PPR	(G - B) / (G + B)	Metternicht 2003
NGRDI	(G – R) / (G + R)	Tucker 1979
NDU	(NIR - R) /	D 1 1074

Redlands, CA, USA).

NDVI

Table 2. Vegetation indices used in this study. B = blue band, G = green band, R = red band, NIR = near infrared band.

(NIR + R)

From the RGB-based orthomosaic the Plant Pigment Ratio (PPR) and Normalized Green Red Difference Index (NGRDI) were derived and from the multispectral orthomosaic the well-known Normalized Difference Vegetation Index (NDVI).

The indices were averaged per plot by calculating zonal statistics using a polygonal shapefile for each plot with an inside buffer of 0.5 m to account for border effects. Biomass samples (n: 156) were upscaled to dry matter yield kg ha<sup>-1</sup>. Linear Regression analysis was performed to test the relationship between dry matter yield and the above-mentioned vegetation indices. Analysis was performed in the statistical computation software R v3.5 (R Core Team 2013). To assess the predictive performance of the VIs, leave-one-out cross-validation was implemented in the regression analysis using the *caret*-package (Kuhn et al., 2018). Prediction accuracy was quantified by calculating the coefficient of determination ( $R^2$ ) and root mean squared error (RMSE).

# 3. RESULTS

Table 3 displays the descriptive statistics for dry biomass yield in kg / ha. The response of biomass to the fertilizer treatments is clearly distinguishable, although the variety between N3 and N4 is less pronounced.

Dry biomass yield [kg / ha]							
	Mean	Median	Min	Max	SD		
N1	1199.56	1164.59	706.82	2051.55	247.98		
N2	1990.20	1987.08	1340.77	2462.87	217.10		
N3	2578.52	2523.47	2077.27	3375.84	278.80		
N4	2789.59	2813.01	2108.69	3425.19	312.39		

Table 3. Descriptive statistics of dry biomass yield for each treatment (SD: standard deviation).

A more detailed view of the orthomosaics is provided in Figures 2 and 3. The pattern of the treatments is clearly visible, also the high similarity of treatments N3 and N4.



Figure 2. Detailed view of Micasense RedEdge-M based orthomosaic (band order 5-4-3). Numbers inside polygons indicate treatments.

Rouse et al. 1974



Figure 3. Detailed view of Sony Alpha 6000 based orthomosaic. Numbers inside polygons indicate treatments.



Figure 4. Detailed view of Micasense RedEdge-M based NDVI map.



Figure 5. Detailed view of Sony Alpha based PPR map.

In Figure 4 and Figure 5 a more detailed view of the NDVI and NGRDI maps are displayed. The treatment pattern is less pronounced in the NDVI map compared to the NGRDI map. For the RGB-based PPR the values are reversed in comparison to the visual appearance and DBY. Higher biomass values correspond to lower index values. The spatial pattern of the treatments is more pronounced in the PPR map.

The relationship of NDVI and PPR to dry biomass yield is depicted in Figures 6 and 7.



The PPR showed a strong negative relationship to DBY with an  $R^2$  of 0.71. The four treatments are clearly visible in the scatterplot (Fig. 6). Higher DBY values are associated with lower PPR values and vice versa. The relationship of NDVI to DBY shows strong saturation effects for higher biomass values.



Figure 8. Measured versus predicted dry biomass yield [kg / ha] for NDVI.



Figure 9. Measured versus predicted dry biomass yield [kg / ha] for PPR.



• N1 • N2 • N3 • N4

Figure 10. Measured versus predicted dry biomass yield [kg / ha] for NGRDI.

The  $R^2$  for the NDVI was 0.63 with an RMSE of 408.30 kg / ha. The PPR had a  $R^2$  of 0.70 with an RMSE of 364.42 kg / ha and the NGRDI a  $R^2$  of 0.57 with a RMSE of 440.83 kg / ha. The pattern between measured and predicted DBY was linear for the PPR, although there was still variation across the regression line. The pattern of the treatments was more pronounced, while N3 and N4 are not distinguishable.

The NGRDI cross-validation result had a similar pattern to the NDVI with saturation effects for the higher fertilized plots.

#### 4. DISCUSSION & CONCLUSION

The aim of this study was to compare simultaneously acquired high resolution RGB and VNIR vegetation indices to predict dry biomass yield in temperate grassland. The results indicate a promising approach to map grassland biomass in high spatial and temporal resolution with consumer-grade RGB cameras. The RGB-based PPR performs well as an indicator of grassland biomass. The lower DNs in the green band and the slightly higher DNs in the blue band of the higher N treatments are linked to carotenoids and chlorophyll. This might explain the better performance of the PPR compared to the NGRDI and NDVI. (Metternicht, 2003). The PPR can distinguish the first (0 kg N/ha) and second (50 kg N/ha) treatment, although it fails to distinguish between the third (100 kg N/ha) and fourth (150 kg N/ha) treatment, similarly to the NGRDI and NDVI. The performance of the NGRDI was similar to the results reported by Lussem et al. (2018) on the same test site, but for a different year. Hunt et al. (2005) reported a good correlation of the NGRDI to alfalfa, corn and soybean biomass, but observed saturation effects for higher biomass yield, which is similar in this study and can be related to Motohka et al. (2010), who observed that RGB-based VIs are limited to certain growing stages. Although the NDVI yields a slightly better cross-validation result than NGRDI, strong saturation effects are clearly visible.

Further investigations should be directed towards the evaluation of high-resolution RGB-based VIs to assess grassland biomass for multiple years, sites and cutting regimes. A combination of spectral features and structural features such as plant height from canopy surface models to predict grassland biomass already shows promising directions to support precision pasture management (Viljanen et al., 2018).

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