

DISCRIMINATION OF TOMATO PLANTS (*SOLANUM LYCOPERSICUM*) GROWN UNDER ANAEROBIC BAFFLED REACTOR EFFLUENT, NITRIFIED URINE CONCENTRATE AND COMMERCIAL HYDROPONIC FERTILIZER REGIMES USING MULTI-SOURCE SATELLITE DATA

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ABSTRACT

We evaluate the detection and discriminative strength of three different satellite spectral settings, namely, HypsIRI, the forthcoming Landsat 9 and Sentinel 2-MSI, in mapping tomato (*Solanum lycopersicum*) plants grown under hydroponic system using human-excreta derived materials (HEDM), namely, anaerobic baffled reactor (ABR) effluent and nitrified urine concentrate (NUC) and commercial hydroponic fertilizer mix (CHFM) as nutrient sources. Partial least squares – discriminant analysis (PLS-DA) and discriminant analysis (DA) were applied to discriminate tomatoes grown under these different nutrient sources. Results of this study showed that spectral settings of HypsIRI sensor can better discriminate tomatoes grown under different fertilizer regimes when compared to Landsat 9 OLI and Sentinel-2 MSI spectral configurations. For instance, based on DA algorithm, HypsIRI exhibited high overall accuracy of 0.99 and a kappa statistic of 0.99 whereas Landsat OLI and Sentinel-2 MSI exhibited over accuracies of 0.94 and 0.95 as well as kappa statistics of 0.79 and 0.85, respectively. Further, the performance of DA was significantly different ($\alpha = 0.05$) from that of PLS-DA based on the MaNemar tests. Overall, the performance of HypsIRI, Landsat 9 OLI-2 and Sentinel-2 MSI data seem to bring new opportunities for crop monitoring at farm scale.

1. INTRODUCTION

Food shortage is a large and growing challenge in sub-Saharan Africa (Mabhaudhi et al. 2016, Van Ittersum et al. 2016). It is estimated that at least one out of four people are hungry and undernourished in Sub-Saharan Africa. The world Bank estimates that in the 2030, nearly 9 in 10 extremely poor people will be living in Sub-Saharan Africa (The-World-Bank 2019). This is exacerbated droughts and soil nutrients deficiencies resulting from limited fertilizer applications (Mabhaudhi et al. 2016, Van Ittersum et al. 2016). This is in turn associated with high fertilizer and food prices, amongst other factors. According to FAO (2019) the Annual food inflation in increased from 5% in 2014 to 6% in 2018 whereas in Europe it remained stable and declined in Latin America, Asia, and Oceania. Subsequently, the improvement of crop production which leads to food security has been amongst the principal priorities required to fulfill the goals of sustainable human development as well as the African Union's Agenda 2063 (Conceição et al. 2016). Furthermore, food demand is anticipated to triple in sub-

Saharan Africa after the projected 2.5-fold increase in population increase (Van Ittersum et al. 2016). Specifically, a 60% increase in agricultural and horticultural production will be required by the increasing population in the light of diminishing water and soil nutrient resources (Nordey et al. 2017). The major concern is that current dietary transition, which is in favour of vegetables such as tomatoes amongst other crops, is projected to increase, especially in urban areas, while water and soil nutrients are on a decline.

Vegetables such as tomatoes play a critical dietary role of providing folate, vitamin A, C and E as well as antioxidants (lycopene, beta-carotene, gamma-carotene), trace elements of flavonoids, phytosterols and water-soluble vitamins important for human health (Beecher 1998). To circumvent the challenge of decreasing soil nutrients and increase the production of vegetables (tomatoes), within a small land area, efforts have been exerted towards improving soil fertility and reducing expenses associated with commercial hydroponic fertilizer mix (CHFM) through the use of anaerobic Baffled Reactor (ABR) effluents and Nitrified Urine Concentrate (NUC) both as a source of soil nutrients

and water (Smith and Smith 2017, Busari et al. 2019). Smith and Smith (2017), for instance, noted that nitrogen recovered from wastewater supported a high increase in tomato (*Solanum lycopersicum*) plant canopy volume, flower and fruit production when compared to plants treated with commercial hydroponic fertilizer mix (CHFM) which contained N, P, K, Ca, Mg, and Si. Al-Hamdan, Cruise et al. (2014) in Jordan noted that treatment of tomato crop using waste water facilitated an increased their fruit size by up to 2 cm in diameter, and weight up to 78.7 g in relation to those administered with potable water in their field experiment. However, the challenge that has been lurking in the agricultural sector is the lack of comprehensive spatial explicit frameworks as well as objective criterion for crop growth and productivity monitoring. Currently, Spatially explicit information on vegetable crop growth, productivity or health status was previously measured in-situ or done through routine field surveys (Al-Lahham et al. 2003, Petropoulos et al. 2018). Despite the fact that these in-situ methods obtained plausible levels of accuracy in characterizing crops, they lacked spatial representativeness. Subsequently, there is need for spatial explicit techniques that can be operational used not only to characterize the crop areal extent, but also their physiognomies. This information can help deduce and understand crop growth and productivity patterns, which are critical in ensuring food security and coming up with well-informed intervention mechanisms, or management strategies were necessary.

Meanwhile, earth observation technologies offer spatially explicit non-destructive synoptic views, innovative and economically feasible timely spatial scale means of generating farm scale crop monitoring. For example, literature shows that remotely sensed data is robust and very sensitive to subtle vegetation traits such as those induced by different water and nutrient regimes Rajah et al. (2015) showed that hyperspectral remotely sensed data could discriminate common dry beans that were rain-fed from those that were irrigated. Lu et al. (2018) discriminated tomato crops that were infected with multi-diseases at different phenological stages using hyperspectral data. Their exhibited results a high overall classification accuracy of 100% in discriminating multi-diseases healthy, asymptomatic and late stage leaves. Above all, the advent and advancement of earth observation facilities has unveiled opportunities for assessing previously unresolved crop growth and productivity related questions linked to plant physiognomies (Petropoulos et al. 2018). Despite Hyperspectral data trade-off between cost and accuracy, it remains the most accurate spatial data for monitoring crop growth and productivity. The sensor has numerous contiguous spectral channels that with the ability to detect and characterize subtle differences in plant traits when compared to other satellite data types. For example, multispectral sensors like Landsat, Satellite Pour l'Observation de la Terre (SPOT), MODerate Resolution Imaging Spectroradiometer (MODIS) are characterized with broad bands making it difficult to discern subtle plant traits as they tend to mask out critical plant information.

Despite the fact that narrow band spectral data offer optimal datasets due to the previously highlighted limitations, a

number of sensors have been or are being developed with improved sensing capabilities (Transon et al. 2018). For example, the earth observation community recently witnessed the launching of Sentinel 2 multispectral imager (MSI) and Landsat 8 OLI etc. Sentinel 2 has been the first freely available sensor a set of spectral wavebands covering the red edge section of the electromagnetic spectrum (B5 (705 nm), 6 (740 nm), and 7 (783 nm)) at a relatively fine spatial resolution of 20m. The sensor has a wide swath-width of 290km, coupled with a high spatial resolution 10 m as well as a five-day temporal resolution making it a better facility crop mapping and monitoring. Both sensors (i.e. Sentinel 2 MSI and Landsat 8 OLI) have been tested in various environmental application areas with plausible findings and conclusions (Dube and Mutanga 2015, Ahmadian et al. 2016, Korhonen et al. 2017, Shoko and Mutanga 2017). However, in some instances they have been reported to experience challenges, especially when applied at farm level monitoring. This has been attributed to the presence of broad wavebands which wavebands, which are perceived to be concealing most important information. As a result, now new sensors such as the proposed Landsat 9 OLI-2 (with improved noise-to-signal ratio), EnMAP and HypIRI are being developed. The National Aeronautics and Space Administration agency (NASA) is looking forward to launching the state-of-the art Hyperspectral Infrared Imager (HypIRI) instruments covering the visible and near-infrared section (Vis/NIR) as well as the thermal infrared (TIR). Although these sensors are earmarked for improving on the limitations of the some of the aforementioned sensors, Landsat 8 OLI will not cover some useful portions of the electromagnetic spectrum (red edge) which is instrumental in crop mapping and monitoring. There is a need to evaluate their performance in discriminating subtle vegetation properties in relation to the available broad-band multispectral sensors.

Forthcoming hyperspectral instruments have a potential to supply the much-needed spatially explicit accurate, consistent, information on vegetable crops. Both of these instruments will be spectrometric, covering the spectral ranges of 420-2450 nm and 380-2510 nm at different sampling distances of 6.5 nm for EnMAP's VNIR and 10nm for EnMAP's SWIR section as well as HypIRI's VSWIR (Guanter et al. 2015, Lee et al. 2015). The swath width of HypIRI will be 185 km at 30 and 60 m spatial resolutions whereas EnMAP have 30 km-wide coverage across-track at a ground-sampling unit of 30m. The temporal resolution of EnMAP will be 4 days at the equator whereas that of HypIRI will be 5 days. The fine spectral, spatial and temporal resolutions of these sensors make them relatively more suitable for agricultural applications. The major advantage with such instruments is that they will avail quality data at relatively low costs for data scarce regions such as the sub-Saharan Africa where resources are limited. This study therefore, sought to compare the strength of HypIRI's spectral configuration in relation to Landsat 9 OLI-2 and Sentinel 2 MSI spectral settings in characterizing tomato (*Solanum lycopersicum*) crops grown under commercial hydroponic fertilizer mix, anaerobic baffled reactor effluent and nitrified urine concentrate as nutrient sources.

2. METHODS AND MATERIALS

2.1. Experimental setup

A pot experiment was conducted in a hydroponic system that was set up in a polyethylene tunnel located at Newlands-Mashu Research Station under eThekweni Municipality, Durban, South Africa (29° 46' 25.648"E 30° 58' 28.329" S). The hydroponic system was designed to run three nutrients streams namely, anaerobic baffle reactor (ABR) effluents, nitrified urine concentrate (NUC) and commercial hydroponic fertilizer mix (CHFM) as a control. Each hydroponic system consisted of 150 L tank and the nutrient solution for each system was enclosed in a 100 L container stacked on the ground at the foot of each system.

Six weeks old, seedlings of 'Monica', a determinate tomato cultivar purchased from a local nursery (Sunshine seedlings, Pietermaritzburg, South Africa) were transplanted to 30 cm polyethylene pots filled with pine sawdust as a growing medium. The nutrient solution for each nutrient source was supplied to the plants using a pressure pump (DAB Model K30/70M, DAB Pumps, MarcoPolo, Mestrino, Italy) via a 20 m irrigation line. A 20 cm drip irrigation emitters (2 L) were placed and irrigation was performed at six intervals of 5 min/duration daily using a timer. The study was arranged using a complete randomised design with three replications of five plants each, giving fifteen experimental units per nutrient source.

Tomato plants of the control treatment were irrigated with a commercial hydroponic fertilizer mix (Hydroponic® and Solu-cal®) at the rate of 800 g + 620 g/ 1000 L of water as recommended for hydroponic tomato production; NUC, commercial fertilizer application rate was used as a standard as recommended by Jonsson et al (2004), and ABR effluents with no specified application rate. For the CHFM and NUC treatment, the fertilizer was mixed using municipal tap water whereas for the ABR treatment, only effluent from the anaerobic baffle reactor component was used as nutrient and irrigation source. The experiment was allowed to run for 12 weeks before the crop was harvested. Remote sensing spectral data was collected at vegetative stage (*i.e.* four weeks after transplanting) and two weeks after flowering.

2.2. Remotely sensed data

The Analytic Spectral Device (ASD) FieldSpec instrument was used to acquire the spectral reflectance of tomatoes plants receiving ABR effluents, NUC and CHFM. The spectral data was collected on The ASD measured the radiation at 1.4 intervals for the 350-1000 nm and 2 nm intervals for the 1000-2500 nm spectral regions. The reflectance measurements were conducted using bare fibre-optic held at nadir position ~0.5m above the tomato canopies resulting in a field of view with a diameter of ~0.225m. This diameter was found to be adequate to capture the reflectance of the tomato canopies. The normalization of spectral measurements was conducted after every 5 to 10 spectral measurements, using a standard spectralon. This was done

to circumvent the possible changes in weather conditions as well as irradiance from the sun (Abdel-Rahman et al. 2014). The spectral measurements were conducted under clear skies during the day between 10h00 and 14h00 since this is the time with maximum net radiation. A total of 90 spectral samples were measured on canopies of tomatoes treated with CHFM (n = 30), ABR (n = 30) and NUC (n = 30). In capturing each spectral sample, the instrument recorded radiance of tomato crops 10 times and then provided an average.

2.3. Discriminating tomato plants grown under different fertilizer regimes

Exploratory data analysis was conducted to determine if the data followed a normal distribution curve. Normality test was performed using the Kolmogorov Smirnov test. Further, we assessed spectral separability as well as administered a pre-filter (Adelabu et al. 2014) after hyperspectral data resampling it to HypSPRI, Sentinel-2 MSI and Landsat 8/9 OLI spectral configurations. Resampling was based on the Analysis of Variance test (ANOVA). We then conducted post-hoc test to establish the channels that exhibited significant differences between the spectral data of the tomatoes crops receiving nutrients from ABR effluent, NUC and CHFM.

The other objective of this study was to assess the accuracies of partial least squares discriminant analysis and Discriminant Analysis algorithms in characterizing tomato crops grown under the three fertilizer regimes. In that regard, we used the PLS-DA and the DA to classify the spectral reflectance of tomato crops growing under UNC, UNF and ABR fertilizer treatments. Details about DA and PLS DA are provided in Zhang et al. (2012) and Boulesteix (2004). Prior to conducting PLS-DA and DA, the spectral samples were partitioned into training (70%) and testing (30 %) data. The 30 percent of the samples were used in model accuracy assessment. Specifically, we further computed the overall, producer and user accuracies, as well as the kappa statistics for each set of spectral settings as classified by the two algorithms. To compare the performance of the two algorithms, a McNemar's test was conducted as detailed by Manandhar et al. (2009) and de Leeuw et al. (2006).

3. RESULTS

Normality test resulted showed significant differences between tomato plants treated with different fertilizer combinations based on the spectral settings of HypSPRI, Sentinel-2MSI and Landsat 8/9 OLI (Figure 2). For HypSPRI resampled data, significant differences were observed in the visible, NIR as well as the SWIR portions of the electromagnetic spectrum. Most glaring differences were observed in the NIR portion of the electromagnetic spectrum as illustrated on Figure 2 (a).

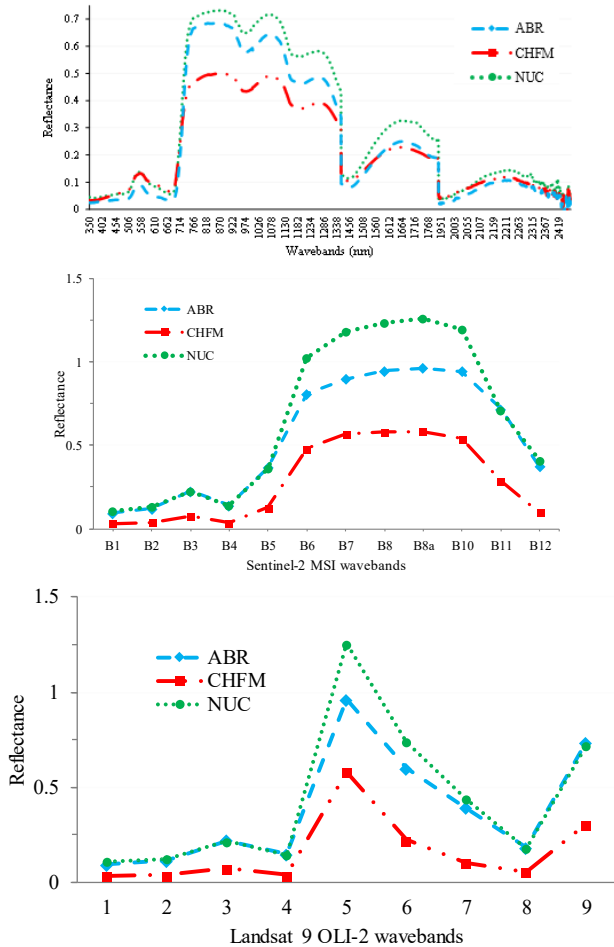


Figure 2: Mean spectral variability of tomatoes under ABR effluent, NUC and CHFMs treatments.

2.4. Discriminating Tomatoes under ABR effluent, NUC and CHFMs

All sensors better characterized tomato crops administered with ABR when compared to those administered with CHFMs and NUC. Specifically, high producer and user accuracies ranging between 91 to 100 % were observed in characterizing tomatoes treated with ABR (Table 2). Meanwhile tomatoes administered with ABR and CHFMs were characterized with slightly lower accuracies (Table 2). Moreover, HypsIRI, produced high accuracies characterized by kappa statistics of 0.99, whereas the spectral settings of Sentinel-2 MSI and Landsat 9 OLI-2’s spectral settings exhibited kappa statistics of 0.85 and 0.79, respectively. HypsIRI spectral settings exhibited high producer accuracies of 100, 92 and 100% for ABR, CHFMs and NUC respectively. Meanwhile resulted in Sentinel-2 MSI exhibited slightly lower producer accuracies (ABR = 91 %, CHFMs = 86 and NUC = 100%). Landsat OLI-2 exhibited producer that were comparable to those of Sentinel 2 MSI which were 91 for ABR, 83 for CHFMs and 100 for NUC. The same trend could be observed on the user accuracies (Table 2)

2.5. Performance of DA and PLS-DA algorithms in discriminating Tomatoes under ABR effluent, NUC and CHFMs

When comparing the performance of algorithms, DA exhibited very high accuracies. For instance, DA’s the producer accuracies derived using DA across all fertilizer treatments and sensor simulations ranged from a minimum of 89% whereas PLS-DA had slightly lower minimum of 83% (Table 2). The user accuracies derived using DA ranged from a minimum of 76% whereas those derived using PLS-DA ranged from 65% to 100. The overall accuracies derived using DA were higher (i.e. 0.94-0.99) when compared to those derived using PLS-DA (i.e. 0.3-0.97). Uniformly, the kappa statistics derived using DA were higher ranging between 0.79 and 0.99 whereas those derived using PLS-DA were lower ranging between 0.63 to 0.90 (Table 2).

Table 2: Classification accuracies derived using HypsIRI, Sentinel 2 MSI and Lands 9 OLI-2 spectral settings

Sensor		PLS-DA		DA		PLS-DA		DA	
		PA	UA	PA	UA	OA	Kappa	OA	Kappa
HypsIRI	ABR	100	95	100	100	0.97	0.90	0.99	0.99
	CHFMs	92	100	100	100				
	NUC	100	94	100	100				
Sentinel 2 MSI	ABR	91	100	100	100	0.90	0.69	0.95	0.85
	CHFMs	86	100	89	100				
	NUC	100	65	100	82				
Landsat 9 OLI-2	ABR	91	95	95	100	0.89	0.63	0.94	0.79
	CHFMs	83	100	89	100				
	NUC	100	65	100	76				

4. DISCUSSION

We sought to compare the strength of HypsIRI's spectral configuration in relation to Landsat 9 OLI-2 and Sentinel 2 MSI spectral settings in characterizing tomato (*Solanum lycopersicum*) crops grown under CHFM, ABR and NUC treatment regimes. Results of this study showed that tomatoes that were fertilized using ABR could be optimally discriminated (i.e. Kappa statistics ranging 0.79 to 0.99) from those that were administered with CHFM and NUC. This could be attributed to the fact that ABR effluents have nutrient properties favorable for tomato plants, which facilitate excessive vegetative growth, high biomass accumulation, delayed or uneven maturity (Maurer et al. 1995, Zavadil 2009, Pedrero et al. 2010). Tomato crops with excessive vegetative growth, high biomass accumulation, delayed or uneven maturity tend to be easily detected and discriminated by satellite sensors compared to those which are not. These tend to make tomatoes growing under the ABR treatments to have a different spectral signature from those that are fertilized using CHFM and NUC. Literature illustrates that ABR tends to facilitate high biomass accumulation (i.e. increased leaf area index) hence the high classification accuracies exhibited by all remotely sensed data in this study (Maurer et al. 1995, Al-Lahham et al. 2003, Zavadil 2009). For example, Al-Lahham et al. (2003) illustrated that tomato crops that were administered with high quantities of waste water had big fruit sizes hence high biomass accumulation in relation to those that were administered with portable water. In a related study, Zavadil (2009) noted that primary treated waste water contained an average of 14-fold nitrogen amounts (70.6 mg/l, which was 89% ammonia form), which also was 3-fold of the total phosphorus which resulted in high yields and therefore biomass accumulation of lettuce salad, radishes, and carrots vegetables in their study of assessing the influence of sewage water on vegetables. Subsequently, the increases in biomass accumulation associated with wastewater treated vegetables could explain the discrimination of ABR treated tomato crops from those administered with CHFM and NUC.

When assessing the performance of sensors, HypsIRI outperformed the two multispectral sensors namely, Sentinel-2 MSI and Landsat OLI spectral settings in discriminating tomato crops grown under different fertilizer regimes. This could be explained that HypsIRI is a hyperspectral sensor characterized by narrow spectral wavebands that are more sensitive to the spectral reflectance of tomato crops grown under different fertilizer regimes than broad band sensor settings such as those of Landsat which could be masking out those minute tomato crops spectral variations. There is consistently growing body of literature that supports the claim that hyperspectral sensors are more sensitive to minute vegetation spectral variabilities compared to broad band sensors due to the narrowed bandwidths configuration (Thenkabail et al. 2002, Thenkabail et al. 2004, Adam et al. 2010, Mansour et al. 2012, Thenkabail and Lyon 2016, Thenkabail 2017). Specifically, Thenkabail et al. (2002) illustrated that narrow bands characterized different crop traits such as yield as well as spectral variations when compared to broadband spectral

data. For example, Thenkabail et al. (2002) were able to better characterize wheat from barley using hyperspectral. They attributed this to the variation in spectral settings (bandwidths) of the sensors they used. These spectral variations affected the detail that will determine the accuracy of the models for plant trait characterization. Meanwhile, Clark (2017) noted that there was no significant variation in the performance of HypsIRI and Sentinel-2 MSI as well as Landsat OLI in landcover classification of the San Francisco Bay Area in northern California, USA. However, their results confirmed that HypsIRI exhibited higher classification accuracies in their study.

Results of this study illustrated that Sentinel 2 MSI and Landsat 9 performed satisfactorily in discriminating tomatoes grown under different fertilizer regimes, although Sentinel 2 MSI outperformed Landsat OLI. This could be explained by the fact that Sentinel-2 MSI spectral settings cover the red edge portion of the electromagnetic spectrum which is critical in mapping and detecting various vegetation traits. Also there is a large and on-growing body of literature that has illustrated that Sentinel-2 MSI performs better than Landsat OLI in vegetation mapping (Clark 2017, Colkesen and Kavzoglu 2017, Shoko and Mutanga 2017). The study by Colkesen and Kavzoglu (2017) illustrated that Sentinel-2 MSI outperformed Landsat OLI in discriminating alfalfa, sugar beet and bean in the agricultural lands of the Ferizli district, Turkey. Shoko and Mutanga (2017) also illustrated the robustness of Sentinel-2 MSI remotely sensed data in better discriminating C3 *Festuca costata* from the C4 *Themeda triandra* grasses in a mountainous area in South Africa. They also attributed the optimal performance of Sentinel-2 MSI to the presence of red edge bands in discriminating *Festuca* from *Themeda* grasses.

Although this was not the major objective of the study, DA outperformed PLS-DA in discriminating tomato crops grown under different fertilizer regimes. In this study PLS-DA failed to derive unnecessary variables for characterizing tomato crops grown under different fertilizer regimes. On the other hand, there are numerous studies that have illustrated the optimal performance of DA in dimension reduction as well as feature extraction (Filella et al. 1995, Karimi et al. 2005, Pu and Liu 2011).

5. CONCLUSION

The prime objective of this study was to compare the strength of the forthcoming hyperspectral sensor HypsIRI's spectral settings in the context of characterizing the effects of different fertilizer treatment regimes on tomatoes crops. Furthermore, the study assessed the performance of PLS-DA in relation to DA in discriminating tomatoes treated with ABR, NUC and CHFM. Grounded on the results exhibited by this study we conclude that:

- The forthcoming HypsIRI, sensor has the potential to accurately map tomato crops under various fertilizer regimes. Landsat and Sentinel comparable performed to HypsIRI spectral settings.

- DA offers optimal accuracies in characterizing tomatoes grown under different fertilizer regimes when compared to PLS-DA.

These findings are a substantial foundation upon which comprehensive precision agricultural assessments initiatives could be formed. These initiatives are required in order to attain sustainable agriculture as well as food security in regions such as sub Saharan Africa where agricultural crop monitoring is currently hindered by the limited access to robust spatial data sets.

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