# MONITORING LANDSLIDES IN THE MUSSOORIE REGION, UTTARAKHAND USING MULTI-TEMPORAL SAR INTERFEROMETRY WITH SENTINEL-1 IMAGES

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# ABSTRACT:

Occurrence of landslide events are common in the lesser Himalayan region which lie in a tectonically active zone with unstable slopes. The Mussoorie region is situated in the lesser Himalayas and is one of most visited tourist sites of the Uttarakhand state. The region is facing social and economic crisis due to the damage caused by multiple landslide events, which requires continuous monitoring for better planning and rescue operations. This study shows the time series analysis of landslide events occurring in the Mussoorie region using the Persistent Scatterer Interferometry (PSI) technique on Sentinel-1 synthetic aperture radar (SAR) images. The processing steps required to process the Sentinel-1 data stacks using both differential SAR interferometry (DInSAR) and PSI are presented. 13 Sentinel-1A C-band interferometric wide swath (IW) images covering a time period of one year are used for PSI processing, resulting in the generation of 12 differential interferograms. The PSI approach extracted 5593 measurement points in the study area. The one dimensional line of sight (1D LOS) time series displacement estimates obtained from PSI processing show a maximum velocity of - 55.7 mm year<sup>-1</sup> in the radar line of sight (LOS) direction, indicating subsidence. The displacement map further used to characterize the landslide susceptible zones show higher displacement magnitude for areas near Jabarkhet, Bhataghat, Bansagad and Raipur range. Use of more Sentinel-1 images and better DInSAR processing algorithms can improve the displacement estimation and pattern detection.

# 1. INTRODUCTION

### 1.1. Landslide detection and analysis

The Himalayan region is mostly affected by deformation events primarily comprising landslides, subsidence and earthquakes. Landslides in these regions mostly occur due to rainfall during the monsoon period [7]. A series of such events can cause loss of life and property, making severe impact on socio-economic factors in cities and towns with greater population density. The areas prone to these events require near real time monitoring using modern surveying techniques in order to facilitate security and remedial measures. Over the last decade, synthetic aperture radar interferometry (InSAR) has been successfully exploited to measure 1 dimensional line of sight (1D LOS) earth surface movement by generating phase difference images known as interferograms [4]. Surface displacement over a time series can be estimated using multi-temporal SAR interferometry (MT-InSAR) techniques e.g. persistent scatterer interferometry (PSI), small baseline subset approach (SBAS), SqueeSAR, etc.as seen in [1] [3] [4][6]. MT-InSAR algorithms require selection of a set of SAR images with same relative orbit having less spatial and temporal decorrelation. Limitations related to spatial and temporal decorrelation mostly occur in non-urban areas, which result in loss of interferometric coherence causing extraction of less number of measurement pixels from the interferograms [6] [9].

The Sentinel-1 (S-1) mission launched by the European space agency (ESA) provides interferometric wide swath (IW) SAR images with a revisit period of 12 days, spatial coverage of ~250 km and a spatial resolution of  $20 \times 5$  m in range and azimuth respectively. These images are acquired using the terrain observation by progressive scans (TOPS) mode, causing azimuth resolution to be constant over the entire swath [5] [8]. The 12 day revisit along with the employment of a large orbital tube for data

acquisition reduces spatial and temporal decorrelation problems [10]. S-1 TOPS images have been with using InSAR algorithms to study the effect of subsidence in Mexico City by [8] and to understand the dynamics of the Fogo volcanic eruptions by [5]. These images can be processed using the above mentioned MT-InSAR algorithms to generate 1D LOS velocity maps. The displacement maps can then be used to estimate surface movement over a time series, thereby helping in interpretation of the movement pattern.

### 1.2. Objective

This research work focusses on the application of PSI approach on S-1 TOPS images to study the effect of landslides in the Mussoorie region, Uttarakhand and to find out the prominent landslide susceptible zones over the period of study.

#### 1.3. Study area and satellite datasets

The Mussoorie region lies in the Uttarakhand state, near to Dehradun city. The region is well known to tourists, with hill ranges situated east-west parallel to the valleys of Dehradun and Siwaliks. Figure 1 shows the study area. The area involves hill ranges, populous areas involving villages, the Mall road, and the Mussoorie Lake. The city has a population of nearly ~35000, varying with time as more people arrive from summer to autumn season [7]. Local geological conditions and rainfall are prime causes of landslides in this region. Large number of tourists visiting the area along with people staying in villages and towns emphasizes monitoring of the site for deformation events. 13 S-1 TOPS images acquired for a period of one year are used in this study. More details on the dataset used can be seen in Table 1. The next section will provide description of the methodology followed in this study, followed by results and conclusion.



Figure 1. Google earth view of the Mussoorie region

Acquisition	Bperp	Btemp
date	(m)	(days)
26 Nov 2015	169.81	120
20 Dec 2015	93.26	96
13 Jan 2016	111.51	72
06 Feb 2016	115.60	48
01 Mar 2016	9.17	24
18 Apr 2016	0.00	0.00
12 May 2016	54.60	24
05 Jun 2016	93.26	48
29 Jun 2016	19.50	72
23 Jul 2016	102.72	96
16 Aug 2016	70.06	120
09 Sep 2016	35.89	144
03 Oct 2016	102.38	168

Table 1. Sentinel-1 TOPS dataset for the Mussoorie region. Image acquired on 18 April 2016 is taken as the master image.

# 2. METHODOLOGY

In this study, S-1 TOPS data is processed using PSI technique. This can be sub divided into two parts, i.e. generation of a stack of differential interferograms and PSI processing of the differential interferograms. The former uses the Sentinels application platform (SNAP) toolbox while the latter part is processed in StaMPS environment.

# 2.1. Differential interferogram stack generation

Figure 2 shows the procedure for preparing a stack of differential interferograms. S-1 IW TOPS images comprise three sub-swaths named IW1, IW2 and IW3. Each image has to be split into one sub-swath selecting one sub-swath such that it includes the same area ground coverage for all the images. Orbital corrections are applied to remove the orbit related errors. After this, the images are stacked together, resulting in a stack of SAR images. The images can now be co-registered with respect to a master image, chosen among the set of images based on perpendicular and temporal baselines [6]. These images need to be deburst to remove demarcation boundaries from the selected sub-swath. Once deburst, the geographical region of interest can be cropped from the image stack using the subset operation. The image stack is now ready for interferogram formation, which requires multiplication of a pixel with complex conjugate of the corresponding pixel in the other image. Topographic correction can be done using an external digital elevation model (DEM) e.g. SRTM on the interferograms to get a stack of differential interferograms [2] [3] [4] [6].



Figure 2. SNAP workflow for preparation of differential interferogram stack.

# 2.2. PSI processing of S-1 TOPS differential interferograms

The differential interferogram stack can be processed using the PSI approach in the StaMPS environment, provided that the data is converted to StaMPS compatible format. The primary PSI processing steps are reliable PS selection, phase unwrapping and displacement estimation [6] [10]. Figure 2 shows the PSI processing steps. For selecting PS pixels, a set of candidate PS pixels are initially identified based on the pixel amplitude dispersion index, *i.e.* the ratio of standard deviation and mean of the pixels in a time series. The pixels which pass this test are tested for phase stability using their time series phase deviation.

Pixels which are selected in this test are selected as PS pixels. The phase of these pixels contain components from atmospheric error  $\Delta \phi_{am,x,i}$ , surface displacement  $\Delta \phi_{disp,x,i}$ , topographic error  $\Delta \phi_{noise,x,i}$ , noise  $\Delta \phi_{noise,x,i}$  and earth flattening  $\Delta \phi_{flat,x,i}$  as shown in equation (1), where k denotes the number of unknown phase cycles required the unwrap the phase  $\left\{\Delta \phi_{x,i}\right\}_w$  of the *i*<sup>th</sup> pixel in the x<sup>th</sup> interferogram and w is the wrapping operator. In the next step, phase unwrapping is done to unwrap the phase of the selected PS pixels [4] [6] [10]. Once unwrapped, the unwrapped phase  $\Delta \phi_{x,i}$  can be converted to 1D LOS change in range using equation (2), where n is the known number of integer phase cycles,  $\lambda$  is the wavelength and  $\Delta R_{x,i}$  corresponds to change in range for pixel *i* in the x<sup>th</sup> interferogram. The final deliverable is a 1D LOS velocity map showing time series velocity of each PS pixel over the period of study.

$$\left\{ \Delta \phi_{x,i} \right\}_{w} = \Delta \phi_{disp,x,i} + \Delta \phi_{flat,x,i} + \Delta \phi_{atm,x,i} + \Delta \phi_{otopo,x,i} + \Delta \phi_{noise,x,i} + k.2\pi$$
 (1)

$$\Delta \phi_{x,i} = \frac{4\pi}{\lambda} \Delta R_{x,i} + n\pi \tag{2}$$



Figure 3. PSI processing chain for Sentinel-1 TOPS differential interferograms.

# 3. RESULTS

13 S-1 IW TOPS images of the Mussoorie region covering a time period of 15 months are processed using the SNAP toolbox for generating a stack of differential interferograms. One of the image (18 April 2016) is chosen as the master image. The images are first split using the S-1 TOPS split, corrected for orbital correction and then co-registered and resampled with respect to the master image, resulting in 12 geocoded, topography removed differential interferograms. For PSI analysis, the stack of differential interferograms are exported to StaMPS environment. PS candidate selection is done using an amplitude dispersion index value of 0.3, finding 12431 PS candidates. Subsequent to this, phase standard deviation value of 0.005 is chosen, resulting in a final set of 5593 pixels. Further, 3D phase unwrapping is applied to unwrap the interferograms. Change in the unwrapped pixel phase values over the period of study are converted to change in 1D LOS range using equation (2).

Figure 4 shows the 1D LOS velocity map obtained for the Mussoorie region with colorbar representing average displacement rate. It is observed that the area has subsided, with cold colours in the map showing higher magnitude of subsidence, i.e. movement towards the LOS. From the velocity map, it can be seen that the area near Jabarkhet, Bhataghat, Raipur range and Bansagad show higher displacement magnitude. Areas with higher population density, i.e. the villages, the mall road and the mall show little displacement. Figure 5 shows a time series velocity for a sample measurement point in the study area showing that the point has moved downwards over the time series. More images of the study area processed in time series can provide more insights about the deformation pattern.



Figure 4. 1D LOS velocity plot of the Mussoorie region obtained from PSI approach.



Figure 5. Time series velocity plot for a sample ps pixel.

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